



# SNS COLLEGE OF ENGINEERING

Kurumbapalayam(Po), Coimbatore – 641 107 Accredited by NAAC-UGC with 'A' Grade Approved by AICTE, Recognized by UGC & Affiliated to Anna University, Chennai

**Department of Information Technology** 

## **Computer Graphics**

### **Unit 2 : TRANSFORMATIONS - ROTATION**

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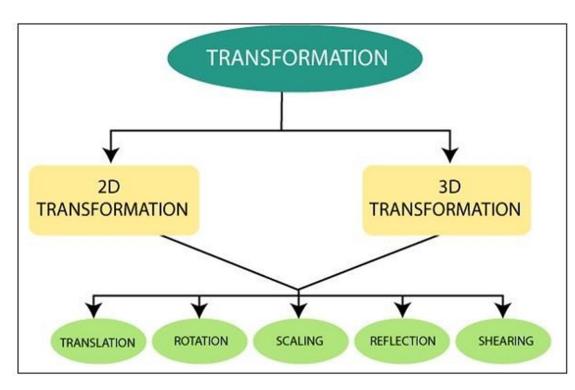
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➤ In computer graphics, transformation refers to the process of changing the position, size, or orientation of an object.

> It is used to manipulate and animate objects in a virtual environment.





# ROTATION



2D Rotation is a process of rotating an object with respect to an angle

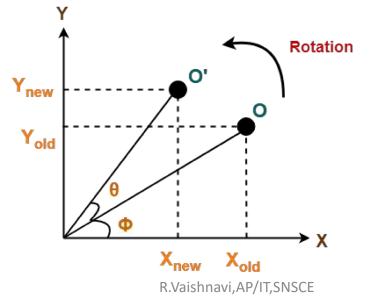
in a two-dimensional plane.

Let

Initial coordinates of the object O = (Xold, Yold)Initial angle of the object O with respect to origin =  $\Phi$ 

Rotation angle =  $\theta$ 

New coordinates of the object O after rotation = (Xnew, Ynew)









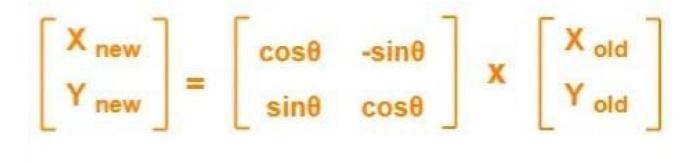
This rotation is achieved by using the following rotation equations

 $Xnew = Xold \ x \ cos\theta - Yold \ x \ sin\theta$ 

 $Ynew = Xold x \sin\theta + Yold x \cos\theta$ 

In Matrix form, the above rotation equations may be represented as-









Given a line segment with starting point as (0, 0) and ending point as

(4, 4). Apply 30 degree rotation anticlockwise direction on the line

segment and find out the new coordinates of the line.

#### **Solution :**

**Problem:** 

We rotate a straight line by its end points with the same angle. Then,

we re-draw a line between the new end points.

Old ending coordinates of the line = (Xold, Yold) = (4, 4)

Rotation angle =  $\theta = 30^{\circ}$ 

Let new ending coordinates of the line after rotation = (Xnew,Ynew).









### Xnew

 $= Xold x \cos\theta - Yold x \sin\theta = Xold x \sin\theta + Yold x \cos\theta$   $= 4 x \cos 30^{\circ} - 4 x \sin 30^{\circ} = 4 x \sin 30^{\circ} + 4 x \cos 30^{\circ}$   $= 4 x (\sqrt{3}/2) - 4 x (1/2) = 4 x (1/2) + 4 x (\sqrt{3}/2)$   $= 2\sqrt{3} - 2 = 2 + 2\sqrt{3}$   $= 2(1 + \sqrt{3})$   $= 2(1 + \sqrt{3})$   $= 2(1 + \sqrt{3})$ = 1.46 = 5.46

Thus, New ending coordinates of the line after rotation = (1.46, 5.46).

**Ynew** 



In matrix form, the new ending coordinates of the line after rotation



may be obtained as-

