



# SNS COLLEGE OF ENGINEERING



Kurumbapalayam(Po), Coimbatore – 641 107

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## Department of AI &DS

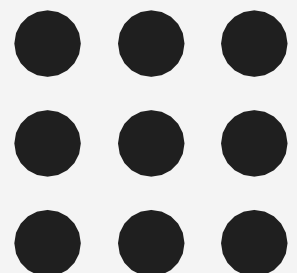
Course Name – 23ADT201 ARTIFICIAL  
INTELLIGENCE

II Year / III Semester

UNIT 3

GAME THEORY

Topic: Constraint Satisfaction Problem and constraint  
propagation





## CASE STUDY

### Background

A university needs to schedule final exams for several courses. The objective is to assign a time slot and room for each exam while ensuring certain constraints are met, such as avoiding conflicts for students enrolled in multiple courses and accommodating room capacities.

## Constraint Satisfaction Problem

- Constraint programming or constraint solving is about finding values for variables such that they **satisfy a constraint(conditions)**.
- $CSP = \{V, D, C\}$ 
  - Variables:**  $V = \{V_1, \dots, V_n\}$
  - Domain:**  $D = \{D_1, D_2, \dots, D_n\}$
  - Constraints:**  $C = \{C_1, \dots, C_k\}$
- **Example:**
  - Crossword puzzle
  - Crypt-Arithmetic problem
  - Map colouring problem

## Crypt-Arithmetic problem

- Crypt-Arithmetic problem is a type of **encryption problem** in which the written message in an alphabetical form which is easily readable and understandable is converted into a numeric form which is neither easily readable nor understandable.







# Constraint Satisfaction Problem and constraint propagation

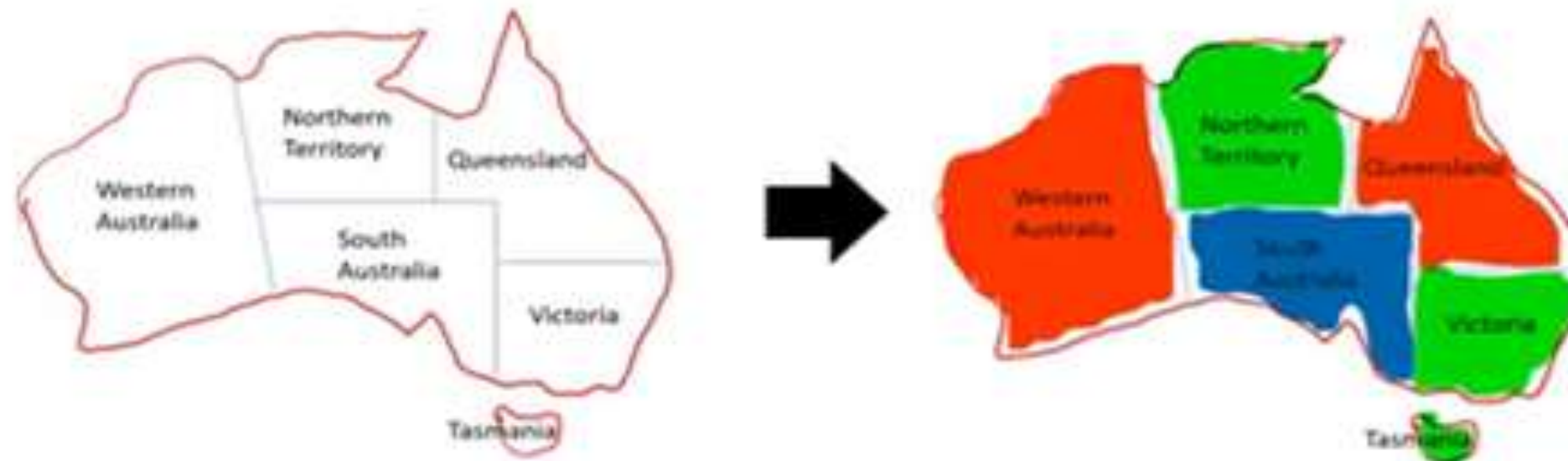


## Constraints

- Every Character must have a **unique value**.
- Digits should be from **0-9** only
- **Starting** character of number **can not be zero**.
- Cryptarithmic problem will have **only one solution**.
- Addition of number with itself is always **even**
- In case of addition of two numbers, if there is carry to next step then, the **carry can only be 1**

## Map Colouring

- Two adjacent regions cannot have the same color no matter whatever color we choose.
- The goal is to assign colors to each region so that **no neighboring regions have the same color.**



## Map Colouring-Example

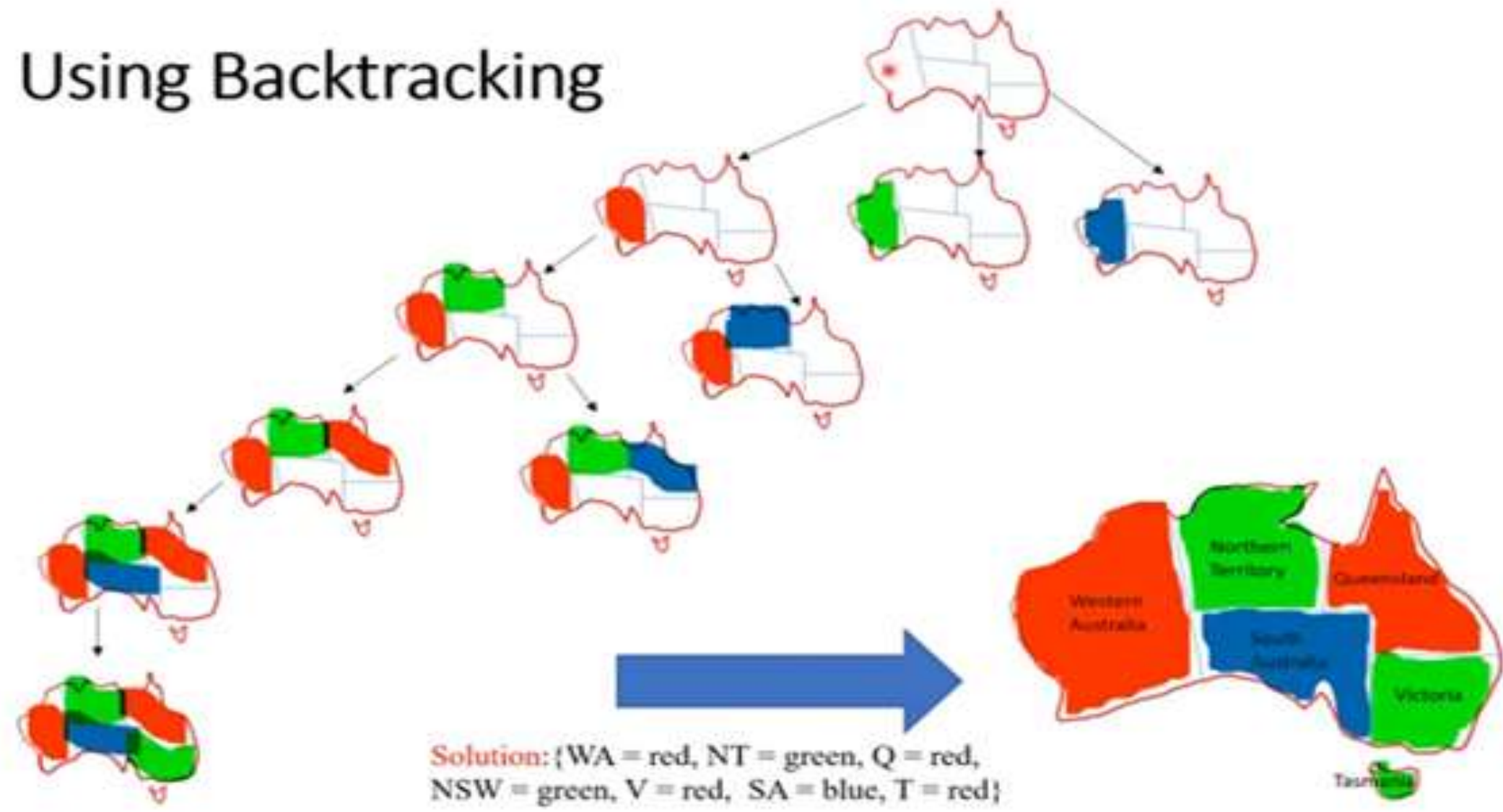
- Color the following map using **red**, **green**, and **blue** such that adjacent regions have different colors
- **Variables:** {WA, NT, Q, NSW, V, SA, T}
- **Domains:** {**red**, **green**, **blue**}
- **Constraints:** adjacent regions must have different colors.  
e.g.,  $WA \neq NT$





# Constraint Satisfaction Problem and constraint propagation

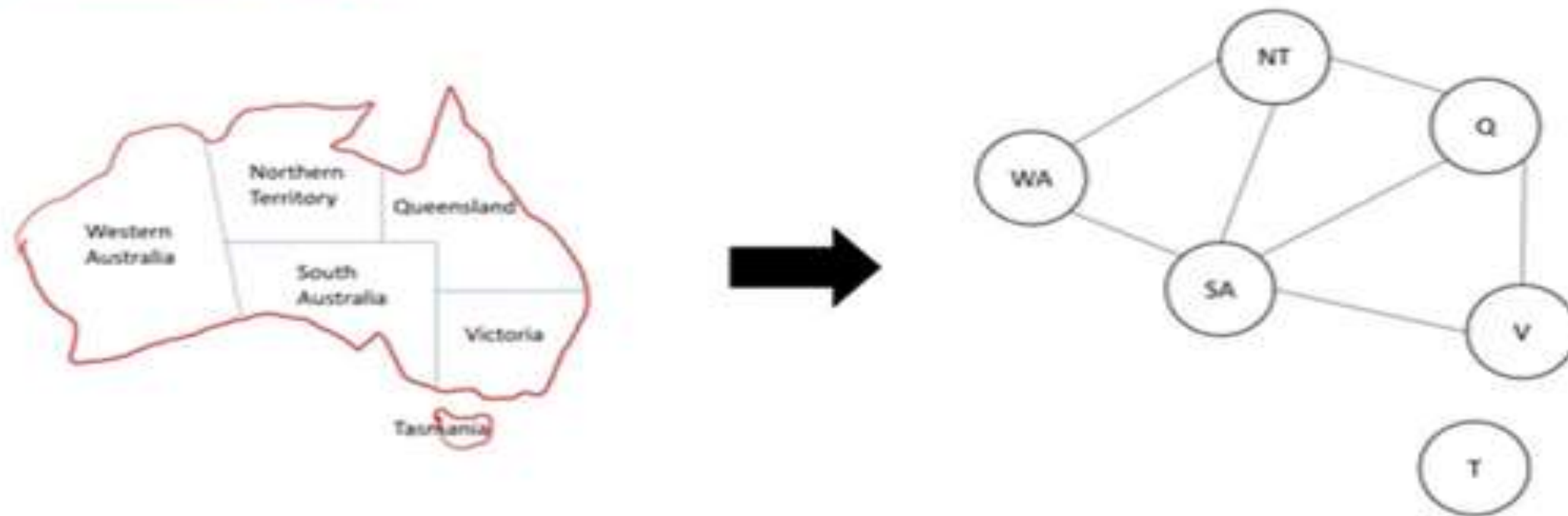
Using Backtracking



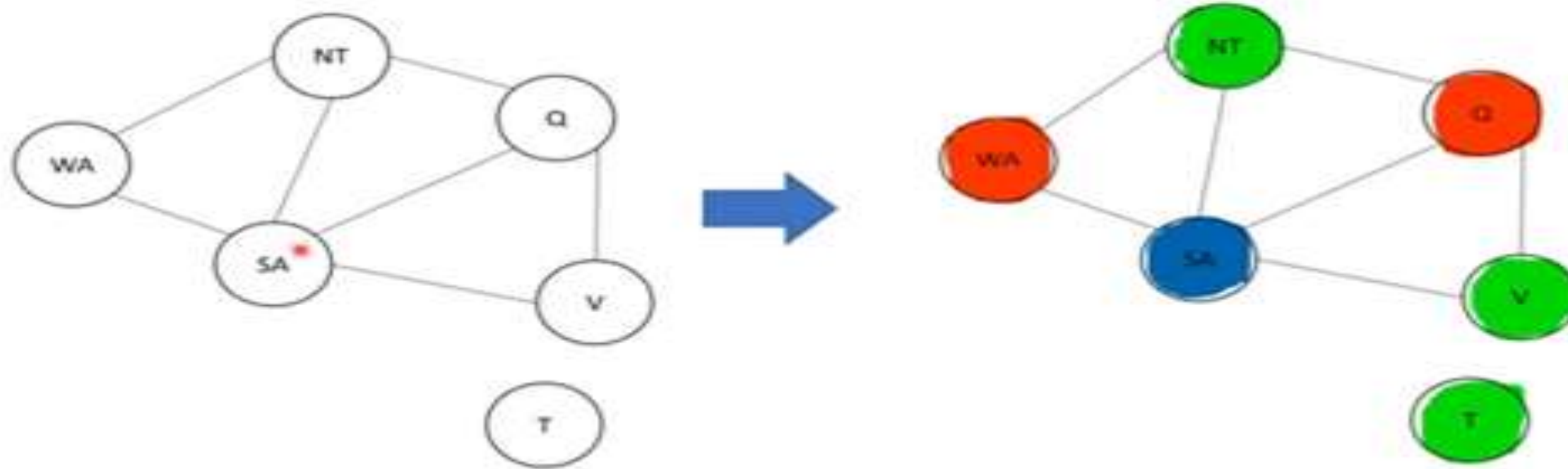


## Constraint Graph

- **Constraint graph:** nodes are variables, arcs are constraints

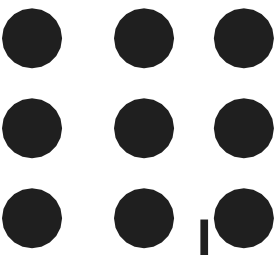


## Constraint Graph





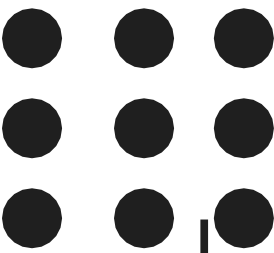
# Constraint Satisfaction Problem and constraint propagation



## Variations on CSP Formalism Variable Types

- Discrete Variables
  - Finite Domains/ Discrete Domains
    - Simplest CSPs define variables that have **discrete, finite domains**.
      - E.g. map coloring, 8-queens.
  - Infinite Domains
    - Domains can be **infinite**
      - e.g. set of integers or strings.
      - E.g. Job scheduling
      - Infinitely many solutions.
      - Thus need to use a constraint language.  **$T1+D1 \leq T2$**
- Continuous Domain
  - e.g. problems from temporal reasoning->time related
  - e.g. problems from spatial reasoning-> space related
  - Hubble telescope



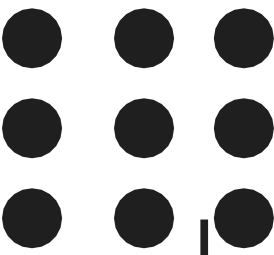


## Variations on CSP Formalism Variable Types

E.g., for a job scheduling problem,

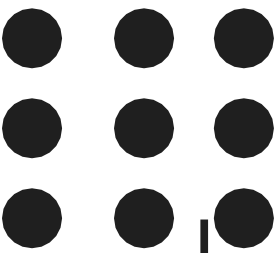
- might have  $T_1 + d_1 \leq T_2$ 
  - where  $T_1$  and  $T_2$  are start times for two tasks and
  - $d_1$  is the duration of the first one





## Variations on CSP Formalism Constraint Types

- The simplest type is the **unary constraint**, which restricts the value of a single variable:
  - $\langle (SA), SA \neq \text{green} \rangle$
- A **binary constraint** relates two variables:
  - $\langle (SA, NSW), SA \neq NSW \rangle$
  - A binary CSP is one with only binary constraints; it can be represented as a constraint graph.
- **Higher-order** constraints are possible.
  - E.g. Between  $(X, Y, Z)$  that specifies that  $Y$  is between  $X$  and  $Z$



## Variations on CSP Formalism Constraint Types

- A constraint involving an arbitrary number of variables is called a **global constraint**.
  - One of the most common global constraints is *Alldiff*.
- Many real-world CSPs include **preference constraints** indicating which solutions are preferred:
  - constraint optimization problem (COP)





# Constraint Satisfaction Problem and constraint propagation



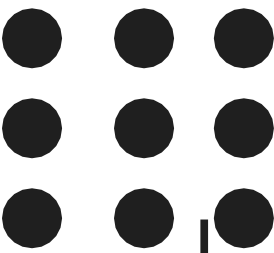
## Convert n-ary constraint to binary one

- Example: How a single ternary constraint such as “ $A + B = C$ ” can be turned into three binary constraints?
  - Using an auxiliary variable:
    - First introduce a new variable  $AB$  and its domain.
    - Then create appropriate relations between the new variables and old ones.





# Constraint Satisfaction Problem and constraint propagation



## Constraint Propagation

- In regular state-space search, an algorithm can do only one thing: search.
- In CSPs there is a choice:
  - an algorithm can search (choose a new variable assignment from several possibilities) or
  - do a specific type of inference called **constraint propagation**
- **Constraint Propagation**
  - using the constraints to reduce the number of legal values for a variable,



## Constraint Propagation

$X = \{WA, NT, Q, NSW, V, SA, T\}$

$D_i = \{red, green, blue\}$

$C = \{SA \neq WA, SA \neq NT, SA \neq Q, SA \neq NSW, SA \neq V, WA \neq NT, NT \neq Q, Q \neq NSW, NSW \neq V\}$

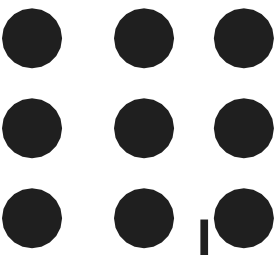


# Constraint Satisfaction Problem and constraint propagation

## Constraint Propagation



	WA	NT	Q	NSW	V	SA	T
WA	Red	Green	Blue	Red	Green	Blue	Red
NT	Red	Green	Blue	Red	Green	Blue	Red
Q	Red	Green	Blue	Red	Green	Blue	Red
NSW	Red	Green	Blue	Red	Green	Blue	Red
V	Red	Green	Blue	Red	Green	Blue	Red
SA	Red	Green	Blue	Red	Green	Blue	Red
T	Red	Green	Blue	Red	Green	Blue	Red



## Local Consistency

- Node consistency
- Arc consistency
- Path consistency
- k-consistency



## Local Consistency Node Consistency

- A single variable is node-consistent if all the values in the variable's domain satisfy the variable's **unary constraints**.

$$X=\{V\}$$

$$D=\{1,2,3,4\}$$

$$C=\{V\leq 3\}$$

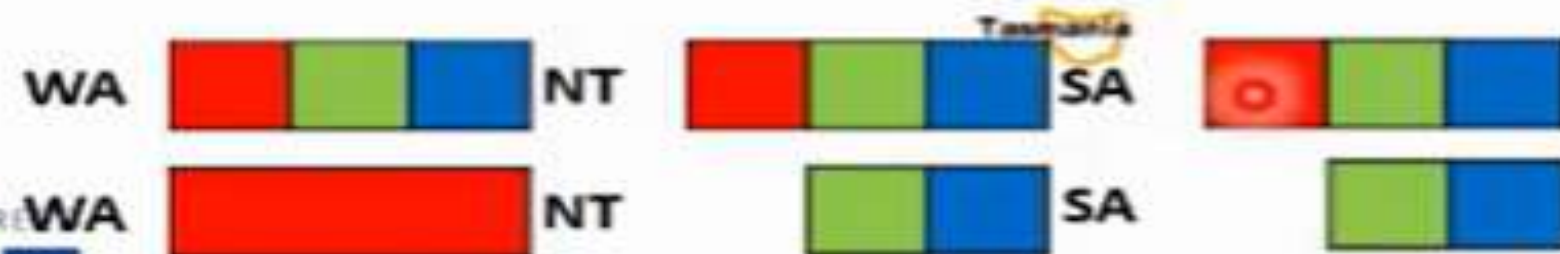
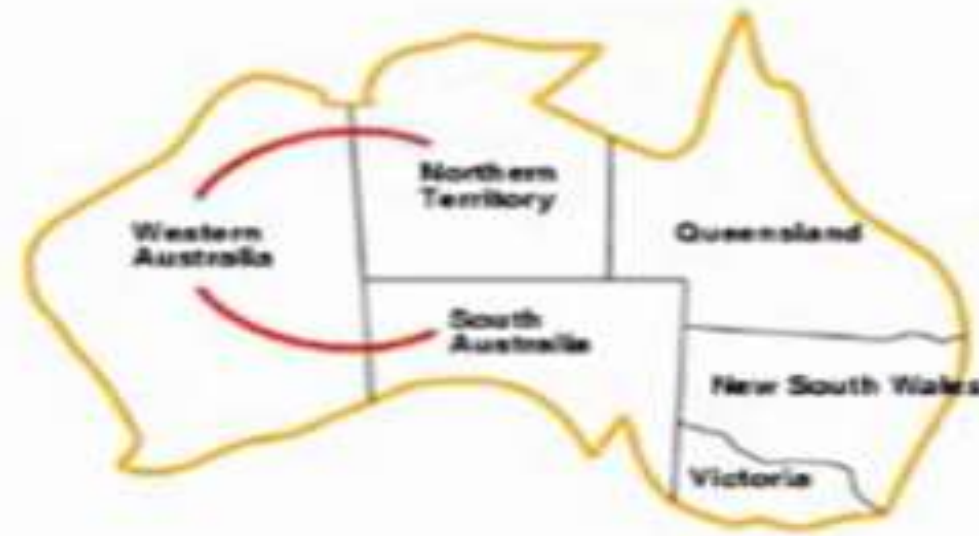
$$\Delta D=\{1,2,3\}$$

- A network is node-consistent if **every** variable in the network is node-consistent.
- It can be done as a preprocessing step:
  - eliminate all inconsistent values from variables' domains.

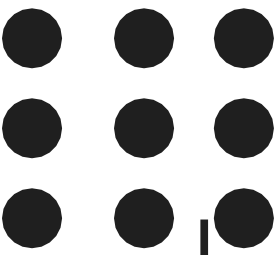


## Local Consistency Arc Consistency

- A variable in a CSP is arc-consistent if **every value** in its domain satisfies the variable's binary constraints.



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## Arc Consistency

- More formally:
  - $X_i$  is arc-consistent with respect to another variable  $X_j$  if
  - for every value in the current domain  $D_i$  there is some value in the domain  $D_j$  that satisfies the binary constraint on the arc  $(X_i, X_j)$ .
- A network is arc-consistent if every variable is arc consistent with every other variable.
- Was there any variable in map coloring problem that was **node** consistent?



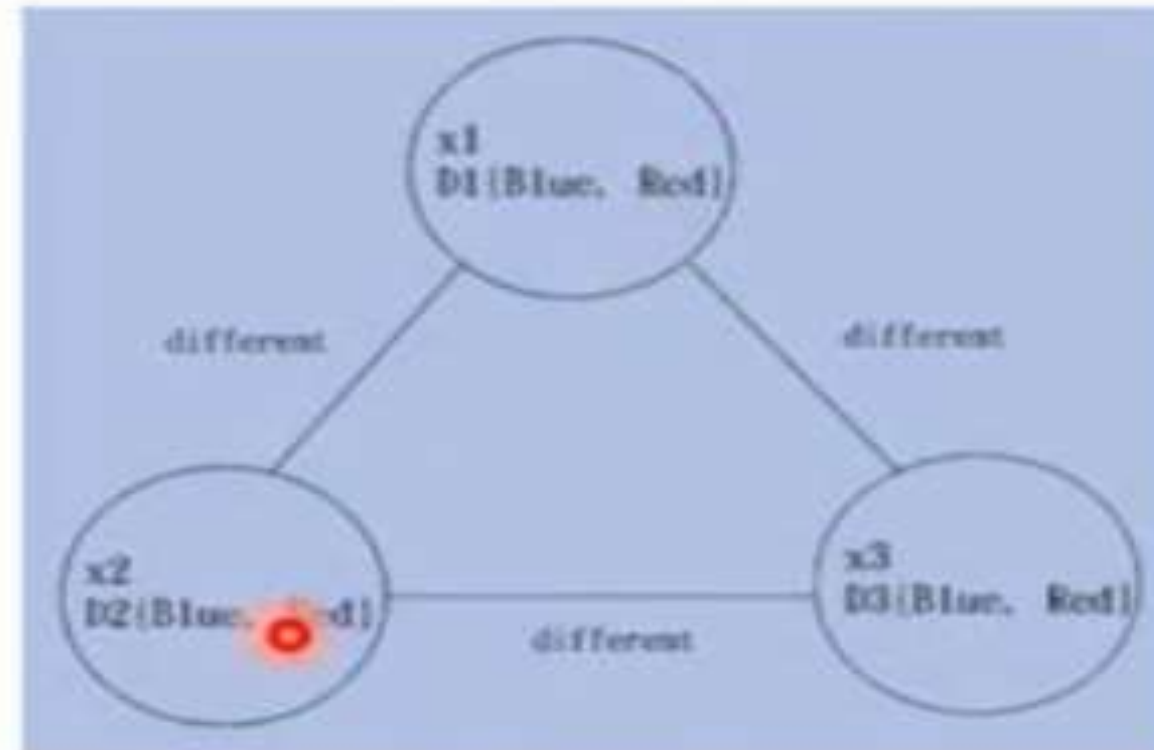
## Local Consistency Path Consistency

- For many kind of problems, arc consistency fails to make enough inferences. Consider the map-coloring problem on Australia, but with only two colors allowed, red and blue...



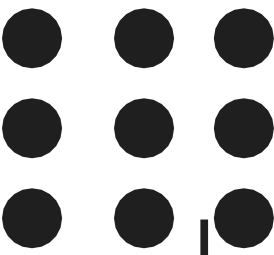
## Local Consistency Path Consistency

- A two-variable set  $\{X1, X2\}$  is path-consistent with respect to a third variable  $X3$  if, for every assignment  $\{X1 = \text{blue}, X2 = \text{Red}\}$  consistent with the constraints on  $\{X1, X2\}$ , there is an assignment to  $X3$  that satisfies the constraints on  $\{X1, X3\}$  and  $\{X3, X2\}$



- This is called path consistency because one can think of it as looking at a path from  $X1$  to  $X2$  with  $X3$  in the middle.



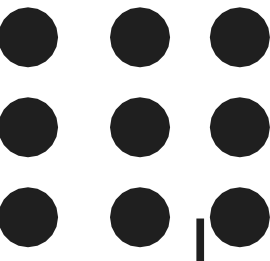


## Local Consistency Path Consistency (Example)

- We will make the set  $\{WA, SA\}$  path consistent with respect to NT .
- We start by enumerating the consistent assignments to the set.
  - In this case, there are only two:  $\{WA = \text{red} , SA = \text{blue}\}$  and  $\{WA = \text{blue}, SA = \text{red}\}$ .
- We can see that with both of these assignments NT can be neither red nor blue.
  - We eliminate both assignments, and we end up with no valid assignments for  $\{WA, SA\}$ .

## Local Consistency K Consistency

- A CSP is  $k$ -consistent if, for any set of  $k - 1$  variables and for any consistent assignment to those variables
  - A consistent value can always be assigned to any  $k$ th variable.
    - 1-consistency: Node consistency.
    - 2-consistency: Arc consistency.
    - 3-consistency: Path consistency.
- A CSP is strongly  $k$ -consistent if it is  $k$ -consistent and is also  $(k-1)$ -consistent,  $(k-2)$ -consistent, . . . all the way down to 1-consistent.



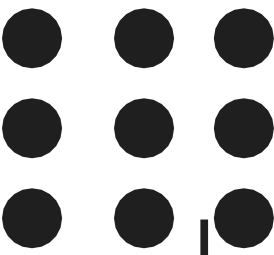
## Local Consistency Find a Solution

- Suppose there is a CSP with  $n$  nodes and strongly  $n$ -consistent. Now a solution can be found in this way:
  - Choose a consistent value for  $X_1$ .
  - It is guaranteed to be able to choose a value for  $X_2$  because the graph is 2-consistent, for  $X_3$  because it is 3-consistent, and so on.
- It is guaranteed to find a solution in time  $O(n^2d)$ :
  - For each variable  $X_i$ , the algorithm only searches through the  $d$  values in the domain to find a value consistent with  $X_1, \dots, X_{i-1}$ .
- Any algorithm for establishing  $n$ -consistency must take time exponential in  $n$  in the worst case.





# Constraint Satisfaction Problem and constraint propagation



# THANK YOU