



UNIT – 4



Describing Curves using Polynomials

1. Basics of Polynomial Curves

Polynomial curves in computer graphics are primarily defined by polynomial functions of a single parameter, usually t , which varies over the interval $[0,1]$. These curves are essential for creating smooth, flowing shapes that can be controlled through mathematical expressions. In general, a polynomial curve of degree n is expressed as:

$$C(t) = a_0 + a_1t + a_2t^2 + \dots + a_nt^n$$

where a_0, a_1, \dots, a_n are coefficients that determine the shape of the curve. For 2D curves, the x and y coordinates are given by polynomial functions of t :

$$\begin{aligned} x(t) &= a_0 + a_1t + a_2t^2 + \dots + a_nt^n \\ y(t) &= b_0 + b_1t + b_2t^2 + \dots + b_nt^n \end{aligned}$$

2. Types of Polynomial Curves

Several types of polynomial curves are widely used in computer graphics. Each type serves different needs depending on the desired control over the curve, smoothness, and complexity.

a. Bézier Curves

- **Definition:** A Bézier curve is a parametric polynomial curve defined by a set of control points. They are often used due to their simplicity and intuitive control.
- **Mathematics:** The degree of the Bézier curve is determined by the number of control points minus one. For instance, a cubic Bézier curve has four control points, $P_0, P_1, P_2,$ and P_3 , and is represented as:

$$B(t) = (1-t)^3P_0 + 3(1-t)^2tP_1 + 3(1-t)t^2P_2 + t^3P_3$$

- **Properties:**
 - **Control:** The curve starts at P_0 and ends at P_3 , with the intermediate points influencing the curve's direction and shape.
 - **Convex Hull:** The curve lies within the convex hull of the control points, ensuring a predictable shape.



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- **Continuity:** Bézier curves are continuous and provide a smooth transition from one point to another.
- **Applications:** Bézier curves are widely used in vector graphics, font design (TrueType fonts), and simple animations.

b. B-Splines (Basis Splines)

- **Definition:** B-Splines are an extension of Bézier curves, providing more flexibility and control by allowing a series of connected curve segments.
- **Mathematics:** B-Splines are defined by a set of control points and a knot vector that dictates where and how each control point affects the curve. The B-Spline function is constructed as a piecewise polynomial, with each piece influenced by several control points.

A B-Spline curve $C(t)$ of degree p with $n+1$ control points P_0, P_1, \dots, P_n is represented as:

$$C(t) = \sum_{i=0}^n N_{i,p}(t) P_i$$

where $N_{i,p}(t)$ are the basis functions defined over the knot vector.

- **Properties:**
 - **Local Control:** Moving one control point affects only the local part of the curve, which is useful in interactive applications like modeling.
 - **Continuity:** B-Splines provide continuous derivatives, ensuring smooth transitions.
 - **Adjustable Smoothness:** The degree of the spline (and the knot vector configuration) controls the curve's smoothness and how tightly it follows the control points.
- **Applications:** B-Splines are used extensively in computer-aided design (CAD), 3D modeling, and animation, where precise control over complex shapes is essential.

c. NURBS (Non-Uniform Rational B-Splines)

- **Definition:** NURBS extend B-Splines by adding weights to control points, allowing for the creation of both standard geometric shapes (e.g., circles) and complex, free-form curves.
- **Mathematics:** A NURBS curve is defined as a weighted sum of B-Spline basis functions:

$$C(t) = \frac{\sum_{i=0}^n N_{i,p}(t) \cdot P_i \cdot w_i}{\sum_{i=0}^n N_{i,p}(t) \cdot w_i}$$



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where $N_{i,p}(t)$ is the B-Spline basis function of degree p , P_i are control points, and w_i are weights associated with each control point.

- **Properties:**
 - **Versatility:** NURBS can represent both free-form curves and exact shapes like circles, which are not possible with standard polynomial curves.
 - **Precision:** By adjusting weights, NURBS can refine the curve shape and add more precise control.
 - **Non-Uniform:** The "non-uniform" part allows for varying spacing in the knot vector, providing more flexibility in curve shaping.
 - **Applications:** NURBS are popular in CAD, automotive, and aerospace industries due to their precision and ability to handle complex shapes accurately.
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3. Properties of Polynomial Curves in Computer Graphics

Polynomial curves have properties that make them especially useful in computer graphics:

Continuity and Smoothness

- Polynomial curves can be constructed to ensure continuity in both position and derivatives, allowing for smooth transitions between connected segments. For instance:
 - **C⁰ continuity:** Ensures the curve is continuous, with no gaps between segments.
 - **C¹ continuity:** Ensures the tangents at connecting points are aligned, providing a smooth curve.
 - **C² continuity:** Ensures curvature continuity, producing even smoother curves.

Convex Hull Property

- Bézier curves and B-Splines respect the convex hull property, meaning the curve is contained within the convex hull of its control points. This provides predictability in curve shape, especially when interacting with control points.

Transformation and Scalability

- Polynomial curves can be easily transformed (e.g., scaling, rotating, translating) by applying these operations to their control points. This property makes them adaptable for different graphics contexts.



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Numerical Stability and Degree Limitation

- Higher-degree polynomials offer more control but can become numerically unstable, causing unwanted oscillations (Runge's phenomenon). This is why lower-degree curves, such as cubic polynomials, are preferred for balancing control and stability.
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4. Applications of Polynomial Curves in Computer Graphics

Polynomial curves are integral to a wide array of applications in computer graphics, each utilizing specific curve types to achieve smoothness and flexibility.

a. 2D Vector Graphics and Font Design

- **Example:** Bézier curves are commonly used in font design (e.g., TrueType fonts). The curve's shape allows letters to be defined with smooth edges that are easy to scale without losing quality.
- **Tools:** Vector graphics tools like Adobe Illustrator use Bézier curves for drawing shapes and outlines due to their intuitive control.

b. 3D Modeling and Animation

- **Example:** B-Splines and NURBS are popular in 3D modeling software (e.g., Maya, Blender) for creating organic shapes like characters, terrain, and objects. NURBS can represent complex surfaces, making them ideal for realistic modeling.
- **Animation:** Polynomial curves are used to define motion paths in animation, allowing objects to follow smooth, controlled trajectories.

c. CAD and Industrial Design

- **Example:** NURBS are widely used in CAD and industrial design to create precise, complex curves that require high accuracy (e.g., car bodies, airplane parts). Their ability to represent both curves and exact geometric shapes makes them indispensable in these fields.
- **Application:** NURBS-based surfaces are used in automotive and aerospace design to ensure both functionality and aesthetics.

d. Motion Graphics and Interactive Applications



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- **Example:** In motion graphics, Bézier curves help create dynamic transitions and effects. By controlling ease-in and ease-out properties, designers can create visually appealing animations.
 - **Interactive Applications:** Polynomial curves enable user-interactive control in applications like drawing tools, where users can manipulate control points to shape curves.
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5. Advantages and Challenges of Using Polynomial Curves

Polynomial curves offer numerous benefits but come with certain challenges.

Advantages

- **Flexibility:** Polynomial curves can be tailored to fit specific needs, with different types providing control over the complexity and smoothness.
- **Mathematical Precision:** They allow for mathematically stable operations like transformations and scaling.
- **Smooth Transitions:** By ensuring continuity in derivatives, polynomial curves facilitate smooth and visually appealing transitions.

Challenges

- **Computational Complexity:** Higher-degree polynomials require more computation, which may impact performance, especially in real-time applications.
- **Numerical Instability:** Higher-degree curves can become numerically unstable, causing oscillations. This is often mitigated by using piecewise polynomials (e.g., splines).
- **Manipulation Complexity:** For more advanced types like NURBS, understanding and controlling weights and knots require specialized knowledge, making them harder to use without proper training.