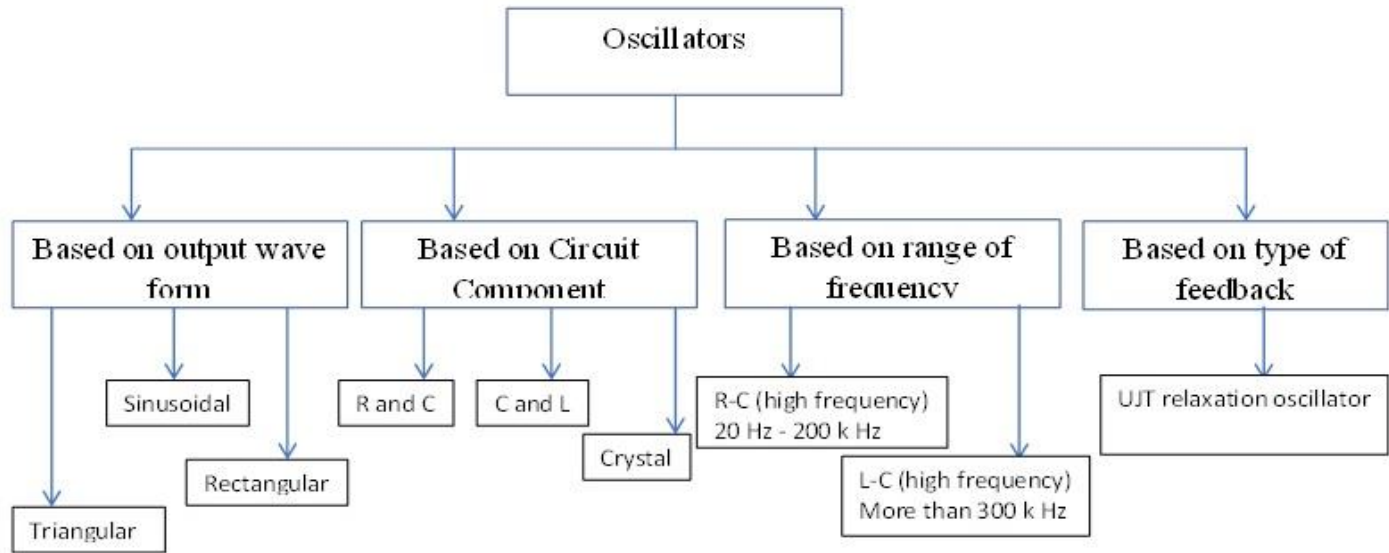


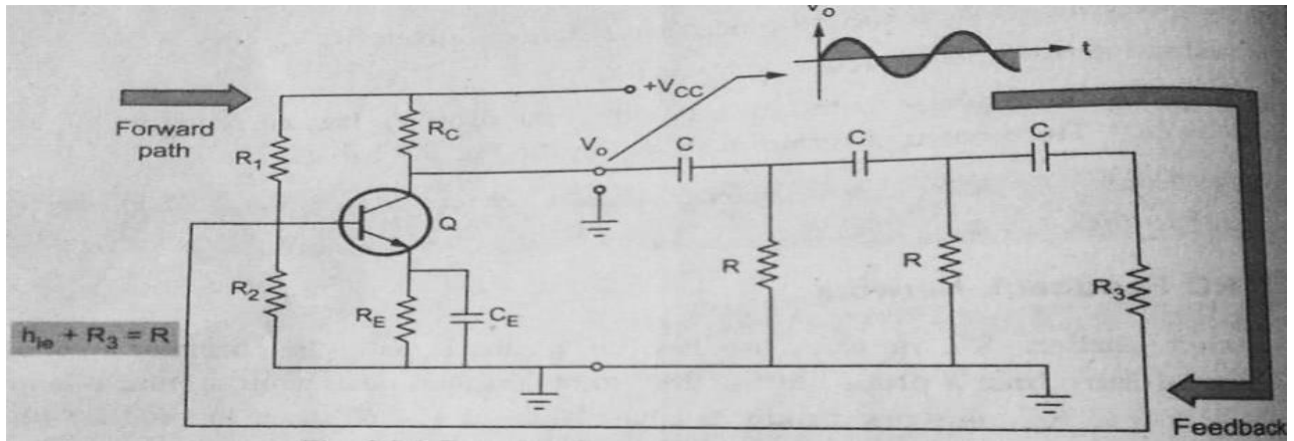
## 1.5 PHASE SHIFT OSCILLATOR

### Classification of oscillator:



### R-C Phase shift Oscillator:

- RC phase shift oscillator basically consists of an amplifier and a feedback network consisting of resistor and capacitors arranged in ladder fashion. Hence such an oscillator is also called ladder type RC phase shift oscillator.
- RC network is used in feedback path. In oscillator, feedback network must introduce a phase shift of  $180^{\circ}$  to obtain total phase shift around a loop as  $360^{\circ}$
- Thus if one RC network produces phase shift of  $\phi=60^{\circ}$  then to produce phase shift of  $180^{\circ}$  such three RC networks must be connected in cascade.
- Hence in RC phase shift oscillator, the feedback network consists of three RC sections each producing a phase shift of  $60^{\circ}$ , thus total phase shift due to feedback is  $180^{\circ}$ .
- Transistorized RC phase shift oscillator, a transistor is used as an active device element of the amplifier.



**Figure: 2.2.1 RC phase shift oscillator**

[Source: *Microelectronics by J. Millman and A. Grabel, Page-386*]

- Fig 2.2.1 shows a practical transistorized RC phase shift oscillator which uses a common emitter single stage amplifier and a phase shifting network consisting of three identical RC sections.
- The output of the feedback network gets loaded due to the low input impedance of a transistor. Hence an emitter follower input stage before the common emitter amplifier stage can be used, to avoid the problem of low input impedance.
- But if only single stage is to be used then the voltage shunt feedback, denoted by resistance  $R_3$  in the figure 2.2.1 is used, connected in series with the amplifier input resistance.
- A phase shifting network is a feedback network, so output of the amplifier is given as an input to the feedback network.
- While the output of the feedback network is given as an input to the amplifier. Thus amplifier supplies its own input, through the feedback network.
- Neglecting  $R_1$  and  $R_2$  as these are sufficiently large,  
 $h_{ie}$ =input impedance of the amplifier stage

$$h_{ie} + R_3 = R$$

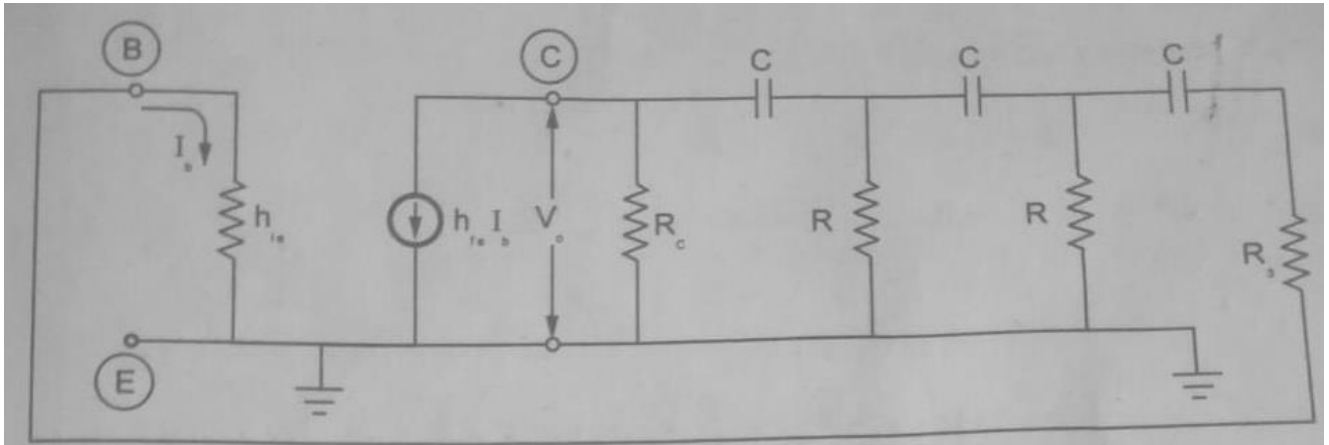
- This ensures that all the three sections of the phase shifting network are identical.

$$R'_i = R_1 || R_2 || h_{ie}$$

$$R'_i + R_3 = R$$

**Derivation for the frequency of oscillations:**

- Replacing the transistor by its approximate h-parameter model, we get the equivalent circuit as shown in the fig 2.2.2



**Figure: 2.2.2 RC phase shift oscillator-equivalent circuit using h-parameter**

[Source: Microelectronics by J. Millman and A. Grabel, Page-386]

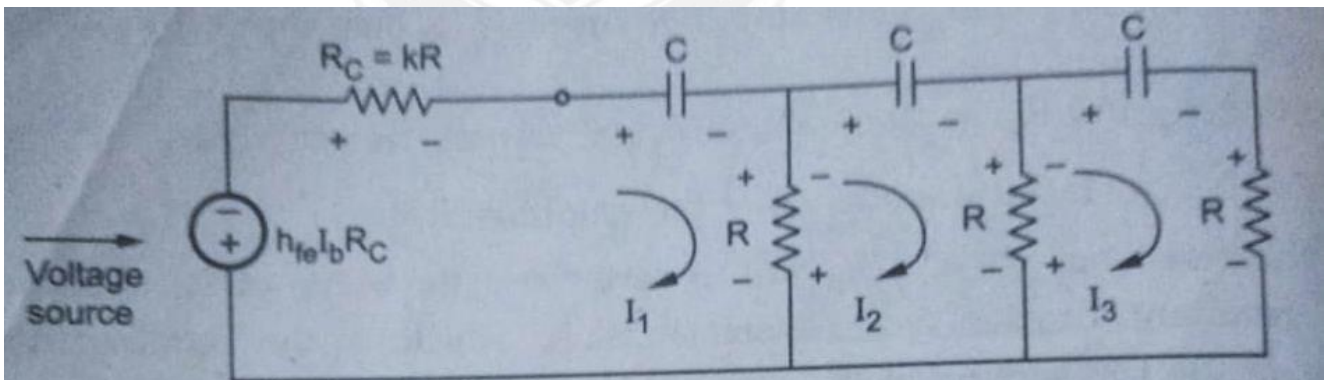
We can replace

$$h_{ie} + R_3 = R$$

And the current source  $h_{fe} I_b$  by its equivalent voltage source

Assume  $k = \frac{R_c}{R}$

- The modified equivalent circuit is shown in fig 2.2.3



**Figure: 2.2.3 RC phase shift oscillator-modified equivalent circuit**

[Source: Microelectronics by J. Millman and A. Grabel, Page-386]

- Applying KVL for the various loops in the modified equivalent circuit we get,  
For loop 1,

$$-I_1 R_c - \frac{1}{j\omega C} I_1 - I_1 R + I_2 R - h_{fe} I_b R_c = 0$$

Replacing  $R_c$  by  $kR$  and  $j\omega$  by  $s$

$$+I_1 \left[ (k+1)R + \frac{1}{sC} \right] - I_2 R = -h_{fe} I_b kR \text{ --- (1)}$$

For loop 2,

$$-I_1 R + I_2 \left[ 2R + \frac{1}{sC} \right] - I_3 R = 0 \text{ --- (2)}$$

For loop 3,

$$-I_2 R + I_3 \left[ 2R + \frac{1}{sC} \right] = 0 \text{ --- (3)}$$

Using Cramer's rule to solve for  $I_3$ ,

$$D = \begin{vmatrix} (k+1)R + \frac{1}{sC} & -R & 0 \\ -R & 2R + \frac{1}{sC} & -R \\ 0 & -R & 2R + \frac{1}{sC} \end{vmatrix}$$

$$D = \frac{s^3 C^3 R^3 [3k+1] + s^2 C^2 R^2 [4k+6] + sRC [5+k] + 1}{s^3 C^3} \text{ --- (4)}$$

Now  $D_3$ ,

$$D_3 = \begin{vmatrix} (k+1)R + \frac{1}{sC} & -R & h_{fe} I_b kR \\ -R & 2R + \frac{1}{sC} & 0 \\ 0 & -R & 0 \end{vmatrix}$$

$$D_3 = -kR^3 h_{fe} I_b \text{ --- (5)}$$

$$I_3 = \frac{D_3}{D}$$

$$I_3 = \frac{-kR^3 h_{fe} I_b s^3 C^3}{s^3 C^3 R^3 [3k+1] + s^2 C^2 R^2 [4k+6] + sRC [5+k] + 1} \text{ --- (5)}$$

$I_3 =$  output current of the feedback circuit

$I_b =$  input current of the amplifier

$I_c = h_{fe}I_b =$  input current of the feedback circuit.

$$\beta = \frac{\text{output of feedback circuit}}{\text{input to feedback circuit}} = \frac{I_3}{h_{fe}I_b}$$

And

$$A = \frac{\text{output of amplifier circuit}}{\text{input to amplifier circuit}} = \frac{I_c}{I_b} = h_{fe}$$

$$A\beta = \frac{I_3}{I_b} \text{ --- (6)}$$

Using equation (6) we get

$$A\beta = \frac{-kR^3h_{fe}s^3C^3}{s^3C^3R^3[3k+1] + s^2C^2R^2[4k+6] + sRC[5+k] + 1} \text{ --- (7)}$$

Substituting  $s=j\omega$ ,  $s^2 = -\omega^2$ ,  $s^3 = -j\omega^3$  in equation (7) and separating real and imaginary part in the denominator we get,

$$A\beta = \frac{+kR^3h_{fe}j\omega^3C^3}{[1 - 4k\omega^2C^2R^2 - 6\omega^2C^2R^2] - j\omega[3k\omega^2R^3C^3 + \omega^2R^3C^3 - 5RC - kRC]}$$

Dividing numerator and denominator by  $j\omega^3C^3R^3$ ,

$$A\beta = \frac{+kh_{fe}}{\left[ \frac{1-4k\omega^2C^2R^2-6\omega^2C^2R^2}{j\omega^3C^3R^3} \right] - \left\{ \frac{j\omega[3k\omega^2R^3C^3+\omega^2R^3C^3-5RC-kRC]}{j\omega^3C^3R^3} \right\}}$$

Replacing  $-1/j = j$  and replacing  $\frac{1}{\omega RC} = \alpha$  for simplicity

$$A\beta = \frac{kh_{fe}}{[-3k - 1 + 5\alpha^2 + k\alpha^2] - j[\alpha^3 - 4k\alpha - 6\alpha]} \text{ --- (8)}$$

As per the Barkhausen criterion  $\angle A\beta = 0^\circ$

Now the angle of numerator term  $kh_{fe}$  of the equation (8) is  $0^\circ$  hence to have angle of the  $A\beta$  term as  $0^\circ$ , the imaginary part of the denominator term must be zero.

$$\alpha^3 - 4k\alpha - 6\alpha = 0$$

$$\alpha = \sqrt{4k + 6}$$

$$\therefore \frac{1}{\omega RC} = \sqrt{4k + 6}$$

$$\omega = \frac{1}{RC\sqrt{4k + 6}}$$

$$f = \frac{1}{2\pi RC\sqrt{4k + 6}}$$

This the frequency at which  $\angle A\beta = 0^\circ$ . at the same frequency  $|A\beta|=1$

Substituting  $\alpha = \sqrt{4k + 6}$  in equation (8) we get

$$h_{fe} = 4k + 23 + \frac{29}{k}$$

This must be the value of  $h_{fe}$  for the oscillations.

To get minimum value of  $h_{fe}$ ,  $\frac{dh_{fe}}{dk} = 0$ ,

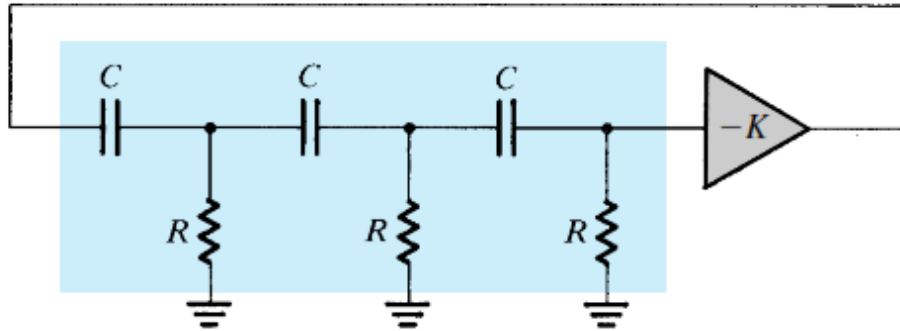
$$k = 2.6925 \text{ for minimum } h_{fe}$$

$$(h_{fe})_{min} = 44.54$$

- Thus for the circuit to oscillate, we must select the transistor whose  $(h_{fe})_{min}$  should be greater than 44.54
- By changing the values of R and C, the frequency of the oscillator can be changed.
- But the value of R and C of all three sections must be changed simultaneously to satisfy the oscillating conditions. But this is practically impossible. Hence the phase shift oscillator is considered as a fixed oscillator, For all practical purpose.

## RC phase shift oscillator using OP-amp

- It consists of a negative gain amplifier ( $-K$ ) with a three-section (third-order) RC ladder network in the feedback.
- the circuit will oscillate at the frequency for which the phase shift of the RC network is  $180^\circ$



**Figure: 2.2.2 RC phase shift oscillator using OP-amp**

[Source: *Microelectronic circuits by sedra and smith, Page-1345*]

- The frequency of oscillation is given by

$$f = \frac{1}{2\pi RC\sqrt{6}}$$

- At this frequency

$$|\beta| = \frac{1}{29}$$

- To have oscillation

$$|A| \geq \frac{1}{\beta} \geq 29$$