

7. Selection of number of teeth :
  - ✓ If not given, assume  $z_1 \geq 17$ . Then  $z_2 = i \times z_1$ .
  - ✓ Virtual number of teeth :  $z_{v1} = \frac{z_1}{\cos \delta_1}$  and  $z_{v2} = \frac{z_2}{\cos \delta_2}$
8. Calculate the transverse module ( $m_t$ ) using the equation 7.28. Then, choose the nearest higher standard transverse module from Table 5.8.
9. Revise the cone distance ( $R$ ) using the relation  $R = 0.5 m_t \sqrt{z_1^2 + z_2^2}$ .
10. Calculation of  $b$ ,  $m_{av}$ ,  $d_{1av}$ ,  $\psi_y$  and  $v$  :
  - ✓ Calculate face width ( $b$ ) :
  - ✓ Calculate average module ( $m_{av}$ ) :  $m_{av} = m_t - \frac{b \sin \delta_1}{z_1}$
  - ✓ Calculate average pcd ( $d_{1av}$ ) :  $d_{1av} = m_{av} \cdot z_1$
  - ✓ Calculate pitch line velocity ( $v$ ) :  $v = \frac{\pi \times d_{1av} \times N_1}{60}$
  - ✓ Calculate  $\psi_y$  : Use  $\psi_y = \frac{b}{d_{1av}}$
11. Select the suitable quality of gear, consulting Table 5.22.
12. Revision of design torque [ $M_t$ ] :
  - ✓ Revise  $K$ , using  $\psi_y$  and Table 5.11.
  - ✓ Revise  $K_d$  using Table 5.12.
  - ✓ Revise [ $M_t$ ], using the revised values of  $K$  and  $K_d$ . Use  $[M_t] = M_t \times K \times K_d$
13. Check for bending :
  - ✓ Calculate the induced bending stress using the equation 7.22.
  - ✓ Compare the induced bending stress with the design bending stress.
  - ✓ If  $\sigma_b \leq [\sigma_b]$ , then the design is satisfactory.
14. If  $\sigma_b > [\sigma_b]$ , then the design is not satisfactory. Then increase the transverse module or face width, or change the gear material. The above procedure is repeated until the design is satisfactory. i.e.,  $\sigma_b \leq [\sigma_b]$ .
15. Check for wear strength :
  - ✓ Calculate the induced contact stress using the equation 7.24.
  - ✓ Compare the induced contact stress with design contact stress.
  - ✓ If  $\sigma_c \leq [\sigma_c]$ , then the design is safe and satisfactory.

**16. Calculation of basic dimensions of the gear pair :** Calculate all the basic dimensions of the pinion and gear using the equations listed in Table 7.1.

**Note**

- ✓ The above listed procedure is for the design of pinion.
  - ✓ As discussed earlier, if the materials of the pinion and gear are same, then design only the pinion. If the materials of the pinion and gear are different, then design the pinion first and check for both pinion and gear.
  - ✓ The induced bending stress in the gear ( $\sigma_{b2}$ ) can be determined by using the relation  $\sigma_{b1} \cdot y_{v1} = \sigma_{b2} \cdot y_{v2}$
- where  $\sigma_{b1}$  and  $\sigma_{b2}$  = Induced bending stresses of pinion and gear respectively, and  $y_{v1}$  and  $y_{v2}$  = Form factors of pinion and gear respectively based on the virtual number of teeth.

- Since the contact area is same, the induced contact stress is same for both pinion and gear. i.e.,  $\sigma_{c1} = \sigma_{c2}$ .

**Example 7.11** Design a cast iron bevel gear drive for a pillar drilling machine to transmit 1875 W at 800 r.p.m. to a spindle at 400 r.p.m. The gear is to work for 40 hours per week for 3 years. Pressure angle is  $20^\circ$ .

**Given Data :**  $P = 1875 \text{ W}$ ;  $N_1 = 800 \text{ r.p.m.}$ ;  $N_2 = 400 \text{ r.p.m.}$ ;  $\alpha = 20^\circ$ .

**To find :** Design a bevel gear drive.

**Solution :** Since the materials of pinion and gear are same, we have to design only the pinion.

**Gear ratio :**

$$i = \frac{N_1}{N_2} = \frac{800}{400} = 2$$

(or)  
8/4 year  
Model  
365/8 = 156  
7 weeks

**Pitch angles :** For right angle bevel gears,  $\tan(\delta_2) = i = 2$  and  $\delta_2 = \tan^{-1}(2) = 63.43^\circ$

$$\delta_1 = 90^\circ - \delta_2 = 90^\circ - 63.43^\circ = 26.57^\circ$$

$$\delta_i = 90^\circ - \delta_2$$

**Material for pinion and gear :** Cast iron, Grade 35 heat treated.

**1. Tensile Strength ( $\sigma_u$ ) :**  $350 \text{ N/mm}^2$ , from Table 5.3

$$\text{Gear life in hours} = (40 \text{ hrs / week}) \times (52 \text{ weeks / year} \times 3 \text{ years}) = 6240 \text{ hours}$$

$$\text{Gear life in cycles, } N = 6240 \times 800 \times 60 = 29.952 \times 10^7 \text{ cycles}$$

**Calculation of initial design torque [ $M_t$ ] :**

$$[M_t] = M_t \times K \times K_d \quad 8.15 \text{ P59}$$

We know that,

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$$\rho = \frac{2\pi N_1 H_t}{S_d}$$

where

$$M_t = \frac{60 \times P}{2\pi \times 800} = \frac{60 \times 1875}{2\pi \times 800} = 22.38 \text{ N-m, and}$$

$$K \cdot K_0 = 1.3,$$

$$[M_t] = 22.38 \times 1.3 = 29.095 \text{ N-m}$$

... (initially assumed)

5. Calculation of  $E_{eq}$ ,  $[\sigma_b]$  and  $[\sigma_c]$ :

Equivalent Young Modulus

→ Table 5.20.

Design bending stress

→ 8.18

where  $K_H = \sqrt{\frac{10^7}{N}}$ 8.19  $K_C = 1.2$ , for C.I., from Table 5.15.8.19  $n = 2$ , from Table 5.17, and8.19  $\sigma_u = 0.45 \sigma_u$ .8.19  $\sigma_{-1} = 350 \text{ N/mm}^2$ , for C.I., from Table 5.3But 140  $\sigma_b = 0.45 \times 350 = 157.5 \text{ N/mm}^2$ ∴ 8.19  $\sigma_{-1} = 0.45 \times 0.8852 \times 157.5 = 81.33 \text{ N/mm}^2$ Then, 8.16  $[\sigma_b] = \frac{1.4 \times 0.8852}{2 \times 1.2} \times 81.33 = 2.3 \times 0.833 \times 498.08 = 498.08 \text{ N/mm}^2$ where 8.16  $C_B = 2.3$ , from Table 5.18,8.16  $(HB) = 200 \text{ to } 260$ , from Table 5.18, and8.17  $K_{cl} = \sqrt[6]{\frac{10^7}{N}} = \sqrt[6]{\frac{10^7}{29.952 \times 10^7}} = 0.833$ , for C.I., from Table 5.19.∴ 8.17  $[\sigma_c] = 2.3 \times 260 \times 0.833 = 498.08 \text{ N/mm}^2$ 6. Calculation of cone distance ( $R$ ):

We know that, 8.18

where 8.18

Bevel

8.16

where 8.16  $\psi_y = R/h = 3$ , initially assumed.

$$R \geq 3 \sqrt{i^2 + 1} \sqrt[3]{\left[ \frac{0.72}{(3 - 0.5) 498.08} \right]^2 \times \frac{1.4 \times 10^5 \times 17905 \times 10^3}{2}}$$

$$R = 51 \text{ mm}$$

Assume  $z_1 = 20$ ; Then  $z_2 = i \times z_1 = 2 \times 20 = 40$ 

$$\text{Virtual number of teeth: } z_{v1} = \frac{z_1}{\cos \delta_1} = \frac{20}{\cos 26.57^\circ} \approx 23; \text{ and}$$

$$z_{v2} = \frac{z_2}{\cos \delta_2} = \frac{40}{\cos 63.43^\circ} \approx 90$$

7. Calculation of transverse module ( $m_t$ ):

$$\text{We know that, } m_t = \frac{R}{0.5 \sqrt{z_1^2 + z_2^2}} = \frac{51}{0.5 \sqrt{20^2 + 40^2}} = 2.28 \text{ mm}$$

From Table 5.8, the nearest higher standard transverse module is 2.5 mm

8. Revision of cone distance ( $R$ ):

$$\text{We know that, } R = 0.5 m_t \sqrt{z_1^2 + z_2^2} = 0.5 \times 2.5 \sqrt{20^2 + 40^2} = 55.9 \text{ mm}$$

9. Calculation of  $b$ ,  $m_{av}$ ,  $d_{1av}$ ,  $v$  and  $\psi_y$ :

$$\checkmark \text{ Face width (b): } b = \frac{R}{\psi_y} = \frac{55.9}{3} = 18.63 \text{ mm}$$

$$\checkmark \text{ Average module (} m_{av} \text{): } m_{av} = m_t - \frac{b \sin \delta_1}{z_1} = 2.5 - \frac{18.63 \times \sin 26.57^\circ}{20} = 2.083 \text{ mm}$$

$$\checkmark \text{ Average pcd of pinion (} d_{1av} \text{): } d_{1av} = m_{av} \times z_1 = 2.083 \times 20 = 41.66 \text{ mm}$$

$$\checkmark \text{ Pitch line velocity (v): } v = \frac{\pi \times d_{1av} \times N_1}{60} = \frac{\pi \times 41.66 \times 10^{-3} \times 800}{60} = 1.745 \text{ m/s}$$

$$\checkmark \text{ To find } \psi_y: \psi_y = \frac{b}{d_{1av}} = \frac{18.63}{41.66} = 0.447$$

1. IS quality 6 bevel gear is assumed, from Table 5.22.

2. Revision of design torque [ $M_t$ ]:

$$\text{We know that, } [M_t] = M_t \times K \times K_d$$

$$8.15$$

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where

$$K = 1.1, \text{ for } b/d_{1av} \leq 1, \text{ from Table 7.2, and}$$

$$K_d = 1.35, \text{ for IS quality 6 and } v \text{ upto } 3 \text{ m/s, from Table 5.12}$$

$$[M_t] = 22.38 \times 1.1 \times 1.35 = 33.24 \text{ N-m}$$

13. Check for bending : We know that the induced bending stress,

$$\sigma_b = \frac{R \sqrt{i^2 + 1} [M_t]}{(R - 0.5 b)^2 \times b \times m_t \times y_{v1}}$$

where  $y_{v1} \approx 0.408$ , for  $z_{v1} = 23$ , from Table 5.13

$$\sigma_b = \frac{55.9 \sqrt{2^2 + 1} \times 33.24 \times 10^3}{(55.9 - 0.5 \times 18.63)^2 \times 18.63 \times 2.5 \times 0.408} = 100.75 \text{ N/mm}^2$$

We find  $\sigma_b > [\sigma_b]$ . Thus the design is not satisfactory.

Trial 2 : Now we will try with increased transverse module 3 mm. Repeating from step again, we get

$$R = 0.5 \times m_t \times \sqrt{z_1^2 + z_2^2} = 0.5 \times 3 \times \sqrt{20^2 + 40^2} = 67.08 \text{ mm}$$

$$b = \frac{R}{\psi_y} = \frac{67.08}{3} = 22.36 \text{ mm}$$

$$m_{av} = m_t - \frac{b \sin \delta_1}{z_1} = 3 - \frac{22.36 \times \sin 26.57^\circ}{20} = 2.5 \text{ mm}$$

$$d_{1av} = m_{av} \times z_1 = 2.5 \times 20 = 50 \text{ mm}$$

$$v = \frac{\pi \times d_{1av} \times N_1}{60} = \frac{\pi \times 50 \times 10^{-3} \times 800}{60} = 2.094 \text{ m/s}$$

$$\psi_y = \frac{b}{d_{1av}} = \frac{22.36}{50} = 0.447$$

IS quality 6 bevel gear is assumed.

$$K = 1.1, \text{ from Table 7.2}$$

$$K_d = 1.35, \text{ from Table 5.12}$$

$$[M_t] = M_t \times K \times K_d = 22.38 \times 1.1 \times 1.35 = 33.24 \text{ N-m}$$

$$\sigma_b = \frac{67.08 \sqrt{2^2 + 1} \times 33.24 \times 10^3}{(67.08 - 0.5 \times 22.36)^2 \times 22.36 \times 3 \times 0.408} = 58.7 \text{ N/mm}^2$$

7.3

Now we find  $\sigma_b < [\sigma_b]$ . Thus the design is satisfactory.

14. Check for wear strength :

$$\sigma_c = \frac{0.72}{(R - 0.5 b)} \left[ \frac{\sqrt{(i^2 + 1)^3}}{i \times h} \times E_{eq} [M_t] \right]^{\frac{1}{2}}$$

$$= \frac{0.72}{(67.08 - 0.5 \times 22.36)} \left[ \frac{\sqrt{(2^2 + 1)^3}}{2 \times 22.36} \times 1.4 \times 10^5 \times 33.24 \times 10^3 \right]^{\frac{1}{2}} = 439.33 \text{ N/mm}^2$$

We find  $\sigma_c < [\sigma_c]$ . Thus the design is satisfactory.

15. Calculation of basic dimensions of pinion and gear : Refer Table 7.1.

✓ Transverse module :  $m_t = 3 \text{ mm}$

✓ Number of teeth :  $z_1 = 20$ ; and  $z_2 = 40$ .

✓ Pitch circle diameter :  $d_1 = m_t \times z_1 = 3 \times 20 = 60 \text{ mm}$ ; and

$$d_2 = m_t \times z_2 = 3 \times 40 = 120 \text{ mm.}$$

✓ Cone distance :  $R = 67.08 \text{ mm}$

✓ Face width :  $b = 22.36 \text{ mm}$

✓ Pitch angles :  $\delta_1 = 26.57^\circ$ ; and  $\delta_2 = 63.43^\circ$

$$d_{a1} = m_t (z_1 + 2 \cos \delta_1) = 3 (20 + 2 \cos 26.57^\circ) = 65.37 \text{ mm}; \text{ and}$$

$$d_{a2} = m_t (z_2 + 2 \cos \delta_2) = 3 (40 + 2 \cos 63.43^\circ) = 122.68 \text{ mm}$$

✓ Height factor :  $f_0 = 1$

✓ Clearance :  $c = 0.2$

$$\tan \theta_{a1} = \tan \theta_{a2} = \frac{m_t \times f_0}{R} = \frac{3 \times 1}{67.08} = 0.0447$$

or

$$\theta_{a1} = \theta_{a2} = 2.56^\circ$$

$$\tan \theta_{f1} = \tan \theta_{f2} = \frac{m_t (f_0 + c)}{R} = \frac{3 (1 + 0.2)}{67.08} = 0.05366$$

$$\theta_{f1} = \theta_{f2} = 3.07^\circ$$

$$\delta_{a1} = \delta_1 + \theta_{a1} = 26.57^\circ + 2.56^\circ = 29.13^\circ; \text{ and}$$

$$\delta_{a2} = \delta_2 + \theta_{a2} = 63.43^\circ + 2.56^\circ = 65.99^\circ$$

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8.39 ✓ Root angle :

$$\delta_{f1} = \delta_1 - \theta_{f1} = 26.57^\circ - 3.07^\circ = 23.5^\circ; \text{ and}$$

$$\delta_{f2} = \delta_2 - \theta_{f2} = 63.43^\circ - 3.07^\circ = 60.36^\circ$$

✓ Virtual number of teeth :  $z_{v1} = 23$ ; and  $z_{v2} = 90$ .

**Example 7.12** Design a straight bevel gear drive between two shafts at right angles to each other. Speed of the pinion shaft is 360 r.p.m. and the speed of the gear wheel shaft is 120 r.p.m. Pinion is of steel and wheel of cast iron. Each gear is expected to work 10 hours / day for 10 years. The drive transmits 9.37 kW.

Given Data:  $\theta = 90^\circ$ ;  $N_1 = 360$  r.p.m.;  $N_2 = 120$  r.p.m.  $P = 9.37$  kW.

To find: Design the bevel gear drive.

① Solution: Since the materials of pinion and gear are different, we have to design the pinion first and check the gear.

1. Gear ratio :

$$i = \frac{N_1}{N_2} = \frac{360}{120} = 3$$

Pitch angles :  $\tan \delta_2 = i = 3$  or  $\delta_2 = \tan^{-1}(3) = 71.56^\circ$

Then,  $\delta_1 = 90^\circ - \delta_2 = 90^\circ - 71.56^\circ = 18.44^\circ$  Tensile stress

2. Material selection : Pinion - C45 Steel,  $\sigma_u = 700$  N/mm<sup>2</sup> and  $\sigma_y = 360$  N/mm<sup>2</sup> Gear - Cl grade 35,  $\sigma_u = 350$  N/mm<sup>2</sup>, from Table 5.3.

3. Gear life in hours =  $(2 \text{ hours/day}) \times (365 \text{ days/year} \times 10 \text{ years}) = 7300 \text{ hours}$

∴ Gear life in cycles,  $N = 7300 \times 360 \times 60 = 15.768 \times 10^7$  cycles

4. Calculation of initial design torque [ $M_t$ ] :

We know that, 8.15  $[M_t] = M_t \times K \times K_d$

$$[M_t] = \frac{60 \times P}{2 \pi N_1} = \frac{60 \times 9.37 \times 10^3}{2 \pi \times 360} = 248.6 \text{ N-m, and}$$

$K \cdot K_d = 1.3$ , initially assumed.

$$[M_t] = 248.6 \times 1.3 = 323.28 \text{ N-m}$$

5. Calculation of  $E_{eq}$ ,  $[\sigma_b]$  and  $[\sigma_c]$

8.4 ✓ To find  $E_{eq}$ :  $E_{eq} = 1.7 \times 10^5$  N/mm<sup>2</sup>, from Table 5.20.

✓ To find  $[\sigma_b]$ : We know that the design bending stress for pinion,

$$[\sigma_{b1}] = \frac{1.4 K_{bl}}{n \cdot K_\sigma} \times \sigma_{-1}, \text{ for rotation in one direction}$$

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where

8.19  $K_H = 1$ , for HB  $\leq 350$  and  $N \geq 10^7$ , from Table 5.14,

8.19  $K_\sigma = 1.5$ , for steel pinion, from Table 5.15,

8.19  $n = 2.5$ , steel hardened, from Table 5.17.

8.19  $\sigma_{-1} = 0.25 (\sigma_u + \sigma_y) + 50$ , for forged steel, from Table 5.16.

$$[\sigma_{b1}] = \frac{1.4 \times 1}{2.5 \times 1.5} \times 315 = 117.6 \text{ N/mm}^2$$

✓ To find  $[\sigma_{cl}]$ : We know that the design contact stress for pinion,

$$[\sigma_{cl}] = C_R \cdot HRC \times K_{cl}$$

where 8.16  $C_R = 23$ , from Table 5.18,

8.16  $HRC = 40$  to  $55$ , from Table 5.18, and

8.17  $K_{cl} = 1$ , for steel pinion, HB  $\leq 350$  and  $N \geq 10^7$ , from Table 5.19.

$$[\sigma_{cl}] = 23 \times 50 \times 1 = 1150 \text{ N/mm}^2$$

6. Calculation of cone distance ( $R$ ) :

We know that,  $R \geq \psi_y \sqrt{i^2 + 1} \sqrt{\left[ \frac{0.72}{(\psi_y - 0.5)[\sigma_c]} \right]^2 \times \frac{E_{eq} [M_t]}{i}}$  PSG 8.13

where 8.15  $(\psi_y) = R/b = 3$ , initially assumed.

$$R \geq 3 \sqrt{3^2 + 1} \sqrt{\left[ \frac{0.72}{(3 - 0.5) 1150} \right]^2 \times \frac{1.7 \times 10^5 \times 323.28 \times 10^3}{3}} \geq 99.36$$

$$R = 100 \text{ mm.}$$

7. Assume  $i = 20$ ; Then  $z_2 = i \times z_1 = 3 \times 20 = 60$

Virtual number of teeth :  $z_{v1} = \frac{z_1}{\cos \delta_1} = \frac{20}{\cos 18.44^\circ} \approx 22$ ; and

$$z_{v2} = \frac{z_2}{\cos \delta_2} = \frac{60}{\cos 71.56^\circ} \approx 190.$$

8. Calculation of transverse module ( $m_t$ ) :

We know that,

$$m_t = \frac{R}{0.5 \sqrt{z_1^2 + z_2^2}}$$

$$= \frac{100}{0.5 \sqrt{20^2 + 60^2}} = 3.162 \text{ mm}$$

BEVEL